

IEEE TRANSACTIONS ON ROBOTICS

A PUBLICATION OF THE IEEE ROBOTICS AND AUTOMATION SOCIETY

DECEMBER 2022

VOLUME 38

NUMBER 6

ITREAE

(ISSN 1552-3098)

REGULAR PAPERS

Model Predictive Contouring Control for Time-Optimal Quadrotor Flight	<i>A. Romero, S. Sun, P. Foehn, and D. Scaramuzza</i>	3340
A Comparative Study of Nonlinear MPC and Differential-Flatness-Based Control for Quadrotor Agile Flight	<i>S. Sun, A. Romero, P. Foehn, E. Kaufmann, and D. Scaramuzza</i>	3357
Omni-Swarm: A Decentralized Omnidirectional Visual–Inertial–UWB State Estimation System for Aerial Swarms	<i>H. Xu, Y. Zhang, B. Zhou, L. Wang, X. Yao, G. Meng, and S. Shen</i>	3374
TAMOLS: Terrain-Aware Motion Optimization for Legged Systems	<i>F. Jenelten, R. Grandia, F. Farshidian, and M. Hutter</i>	3395
Dynamic Complementarity Conditions and Whole-Body Trajectory Optimization for Humanoid Robot Locomotion	<i>S. Dafarra, G. Romualdi, and D. Pucci</i>	3414
RBO Hand 3: A Platform for Soft Dexterous Manipulation	<i>S. Puhlmann, J. Harris, and O. Brock</i>	3434
So-EAGlove: VR Haptic Glove Rendering Softness Sensation With Force-Tunable Electrostatic Adhesive Brakes	<i>Q. Xiong, X. Liang, D. Wei, H. Wang, R. Zhu, T. Wang, J. Mao, and H. Wang</i>	3450
Neural-Gas Network-Based Optimal Design Method for ERT-Based Whole-Body Robotic Skin	<i>K. Park and J. Kim</i>	3463
Active Multiobject Exploration and Recognition via Tactile Whiskers	<i>C. Xiao, S. Xu, W. Wu, and J. Wachs</i>	3479
Adaptive Constrained Kinematic Control Using Partial or Complete Task-Space Measurements	<i>M. M. Marinho and B. V. Adorno</i>	3498
Development of an Untethered Adaptive Thumb Exoskeleton for Delicate Rehabilitation Assistance	<i>G. Li, L. Cheng, Z. Gao, X. Xia, and J. Jiang</i>	3514
Density Control of Large-Scale Particles Swarm Through PDE-Constrained Optimization	<i>C. Sinigaglia, A. Manzoni, and F. Braghin</i>	3530
Byzantine Resilient Distributed Learning in Multirobot Systems	<i>J. Li, W. Abbas, M. Shabbir, and X. Koutsoukos</i>	3550
Closed-Loop Motion Control of Robotic Swarms – A Tether-Based Strategy	<i>K. Eshaghi, A. Rogers, G. Nejat, and B. Benhabib</i>	3564
Innate Motivation for Robot Swarms by Minimizing Surprise: From Simple Simulations to Real-World Experiments ...	<i>T. K. Kaiser and H. Hamann</i>	3582
Temporal Logic Task Allocation in Heterogeneous Multirobot Systems	<i>X. Luo and M. M. Zavlanos</i>	3602
Adaptive Multirobot Implicit Control of Heterogeneous Herds	<i>E. Sebastián, E. Montijano, and C. Sagüés</i>	3622
Bidirectional Sampling-Based Motion Planning Without Two-Point Boundary Value Solution	<i>S. Nayak and M. W. Otte</i>	3636
Adaptive Bézier Degree Reduction and Splitting for Computationally Efficient Motion Planning	<i>Ö. Arslan and A. Tiemessen</i>	3655
Energy Autonomy for Robot Systems With Constrained Resources	<i>H. Fouad and G. Beltrame</i>	3675
Autonomous Navigation in Unknown Environments With Sparse Bayesian Kernel-Based Occupancy Mapping	<i>T. Duong, M. Yip, and N. Atanasov</i>	3694
Directional Sensor Planning for Occlusion Avoidance	<i>J. Gemerek, B. Fu, Y. Chen, Z. Liu, M. Zheng, D. van Wijk, and S. Ferrari</i>	3713

(Contents Continued on Page 3339)



(Contents Continued from Front Cover)

Observability-Aware Intrinsic and Extrinsic Calibration of LiDAR-IMU Systems	J. Lv, X. Zuo, K. Hu, J. Xu, G. Huang, and Y. Liu	3734
A Novel Radar Point Cloud Generation Method for Robot Environment Perception	Y. Cheng, J. Su, M. Jiang, and Y. Liu	3754
A Generalized Framework for Concentric Tube Robot Design Using Gradient-Based Optimization	J.-T. Lin, C. Girerd, J. Yan, J. T. Hwang, and T. K. Morimoto	3774
Kinematic Modeling and Characterization of Soft Parallel Robots	X. Huang, X. Zhu, and G. Gu	3792
Design and Optimization of a Multimode Amphibious Robot With Propeller-Leg	X. Ma, G. Wang, and K. Liu	3807
A Soft Robot With Variable Stiffness Multidirectional Grasping Based on a Folded Plate Mechanism and Particle Jamming	H. Wei, Y. Shan, Y. Zhao, L. Qi, and X. Zhao	3821
Malleable Robots: Reconfigurable Robotic Arms With Continuum Links of Variable Stiffness	A. B. Clark and N. Rojas	3832
Learning to Play Table Tennis From Scratch Using Muscular Robots	D. Büchler, S. Guist, R. Calandra, V. Berenz, B. Schölkopf, and J. Peters	3850
From Simulation to Reality: A Learning Framework for Fish-Like Robots to Perform Control Tasks	T. Zhang, R. Tian, H. Yang, C. Wang, J. Sun, S. Zhang, and G. Xie	3861
Model-Based Policy Search Using Monte Carlo Gradient Estimation With Real Systems Application	F. Amadio, A. Dalla Libera, R. Antonello, D. Nikovski, R. Carli, and D. Romeres	3879
Safety-Aware Hierarchical Passivity-Based Variable Compliance Control for Redundant Manipulators	Y. Michel, C. Ott, and D. Lee	3899
An Energy-Based Control Architecture for Shared Autonomy	F. Benzi, F. Ferraguti, G. Riggio, and C. Secchi	3917
Energy Aware Impedance Control of a Flying End-Effector in the Port-Hamiltonian Framework	R. Rashad, D. Bicego, J. Zult, S. Sanchez-Escalonilla, R. Jiao, A. Franchi, and S. Stramigioli	3936
